

Operator's Manual

optris[®] CTvideo

1M/ 2M/ 3M



Infrared-thermometer

Optris GmbH

Ferdinand-Buisson-Str. 14
13127 Berlin
Germany

Tel.: +49 30 500 197-0
Fax: +49 30 500 197-10

E-mail: info@optris.de
Internet: www.optris.de



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1 General Information

1.1 Description

Thank you for choosing the **optris® CTvideo** infrared thermometer.

The sensors of the optris CTvideo series are noncontact infrared temperature sensors.

They calculate the surface temperature based on the emitted infrared energy of objects [**► 10 Basics of Infrared Thermometry**]. The alignment of the sensor can be done with the integrated video sighting and crosshair laser aiming.

The sensor housing of the CTvideo head is made of stainless steel (IP65/ NEMA-4 rating) – the sensor electronics is placed in a separate box made of die casting zinc.



The CTvideo sensing head is a sensitive optical system. Please use only the thread for mechanical installation.



- Avoid abrupt changes of the ambient temperature.
- Avoid mechanical violence on the head – this may destroy the system (expiry of warranty).
- If you have any problems or questions, please contact our service department.



Read the manual carefully before the initial start-up. The producer reserves the right to change the herein described specifications in case of technical advance of the product.



► All accessories can be ordered according to the referred part numbers in brackets [].

1.2 Warranty

Each single product passes through a quality process. Nevertheless, if failures occur please contact the customer service at once. The warranty period covers 24 months starting on the delivery date. After the warranty is expired the manufacturer guarantees additional 6 months warranty for all repaired or substituted product components. Warranty does not apply to damages, which result from misuse or neglect. The warranty also expires if you open the product. The manufacturer is not liable for consequential damage or in case of a non-intended use of the product.

If a failure occurs during the warranty period the product will be replaced, calibrated or repaired without further charges. The freight costs will be paid by the sender. The manufacturer reserves the right to exchange components of the product instead of repairing it. If the failure results from misuse or neglect the user has to pay for the repair. In that case you may ask for a cost estimate beforehand.

1.3 Scope of Supply

- CTvideo sensing head with connection cable and electronic box
- Mounting nut and mounting bracket (fixed)
- 5 m USB cable
- Software CompactConnect
- Operators manual

1.4 Maintenance

Lens cleaning: Blow off loose particles using clean compressed air. The lens surface can be cleaned with a soft, humid tissue moistened with water or a water based glass cleaner.



Never use cleaning compounds which contain solvents (neither for the lens nor for the housing).

1.5 Model Overview

The sensors of the CTvideo series are available in the following basic versions:

Model	Model code	Measurement range	Spectral response	Typical applications
CT video 1M	1ML	485 to 1050 °C	1,0 µm	Metals and ceramic surfaces
	1MH	650 to 1800 °C		
	1MH1	800 to 2200 °C		
CT video 2M	2ML	250 to 800 °C	1,6 µm	Metals and ceramic surfaces
	2MH	385 to 1600 °C		
	2MH1	490 to 2000 °C		
CT video 3M	3ML	50 to 400 °C	2,3 µm	Metals at low object temperatures (ab 50 °C)
	3MH	100 to 600 °C		
	3MH1	150 to 1000 °C		
	3MH2	200 to 1500 °C		
	3MH3	250 to 1800 °C		

In the following chapters of this manual you will find only the short model codes.

On the 1M, 2M, 3M models the whole measurement range is split into several sub ranges (L, H, H1 etc.).

1.6 Factory Default Settings

The unit has the following presetting at time of delivery:

Signal output object temperature	0-5 V								
Emissivity	1,000								
Transmissivity	1,000								
Average time (AVG)	inactive								
Smart Averaging	active								
Peak hold	inactive								
Valley hold	inactive								
	1ML	1MH	1MH1	2ML	2MH	2MH1	3ML	3MH	3MH1
Lower limit temperature range [°C]	485	650	800	250	385	490	50	100	150
Upper limit temperature range [°C]	1050	1800	2200	800	1600	2000	400	600	1000
Lower alarm limit [°C] (normally closed)	600	800	1200	350	500	800	100	250	350
Upper alarm limit [°C] (normally open)	900	1400	1600	600	1200	1400	300	500	600

	3MH2	3MH3	
Lower limit temperature range [°C]	200	250	
Upper limit temperature range [°C]	1500	1800	
Lower alarm limit [°C] (normally closed)	550	750	
Upper alarm limit [°C] (normally open)	1000	1200	
Lower limit signal output	0 V		
Upper limit signal output	5 V		
Temperature unit	°C		
Ambient temperature compensation	internal head temperature probe		
Baudrate [kBaud]	115		
Laser	inactive		



Smart Averaging means a dynamic average adaptation at high signal edges.

[Activation via software only].

► **Appendix C – Smart Averaging**

2 Technical Data

2.1 General Specifications

	Sensing head	Electronic box
Environmental rating	IP65 (NEMA-4)	
Ambient temperature ¹⁾	-20...70 °C	-20...85 °C
Storage temperature	-40...85 °C	
Relative humidity	10...95 %, non condensing	
Material	stainless steel	die casting zinc
Dimensions	116 mm x 50 mm, M48x1,5	89 mm x 70 mm x 30 mm
Weight	600 g	420 g
Cable length	3 m (standard), 5 m, 10 m	
Cable diameter	5 mm	
Ambient temperature cable		
Cable sensing head-electronics	max. 80 °C [High temperature cable (optional): 180 °C]	
USB-cable	max. 80 °C	
Vibration	IEC 68-2-6: 3G, 11 – 200 Hz, any axis	
Shock	IEC 68-2-27: 50G, 11 ms, any axis	
Software (optional)	CompactConnect	

¹⁾ Laser will turn off automatically at ambient temperatures >50 °C. The functionality of the LCD display can be limited at ambient temperatures below 0 °C.

2.2 Electrical Specifications

Power Supply	8–36 VDC
Current draw	max. 160 mA
Aiming laser	635 nm, 1 mW, On/ Off via programming keys or software
Video sighting	Digital (USB 2.0), 640 x 480 px, FOV 3.1° x 2.4°
Output/ analog	selectable: 0/ 4–20 mA, 0–5/ 10 V, thermocouple (J or K) or alarm output (Signal source: object temperature)
Alarm output	Open collector output at Pin AL2 [24 V/ 50 mA]
Output impedances	
mA	max. loop resistance 500 Ω (at 8-36 VDC)
mV	min. 100 k Ω load impedance
Thermocouple	20 Ω
Digital interface	USB 2.0
Functional inputs	<p>F1-F3; software programmable for the following functions:</p> <ul style="list-style-type: none"> • external emissivity adjustment • ambient temperature compensation • trigger (reset of hold functions) <p>Input impedance F2 and F3: 43 kΩ</p>

2.3 Measurement Specifications [1M models]

	1ML	1MH	1MH1
Temperature range (scalable)	485...1050 °C	650...1800 °C	800...2200 °C
Spectral range	1,0 µm		
Optical resolution	150:1	300:1	
System accuracy ^{1), 2), 3)}	±(0,3 % of reading +2 °C)		
Repeatability ^{1), 3)}	±(0,1 % of reading +1 °C)		
Temperature resolution (NETD)	0,1 K		
Exposure time (90% signal) ⁴⁾	1 ms		
Emissivity/ Gain	0,100...1,100 (adjustable via programming keys or software)		
Transmissivity	0,100...1,100 (adjustable via programming keys or software)		
Signal processing	Average, peak hold, valley hold (adjustable via programming keys or software)		

¹⁾ at ambient temperature 23±5 °C

²⁾ Accuracy for thermocouple output: ±2,5 °C or ±1 %

³⁾ $\varepsilon = 1$ / Response time 1 s

⁴⁾ with dynamic adaptation at low signal levels

2.4 Measurement Specifications [2M models]

	2ML	2MH	2MH1
Temperature range (scalable)	250...800 °C	385...1600 °C	490...2000 °C
Spectral range	1,6 µm		
Optical resolution	150:1	300:1	
System accuracy ^{1), 2), 3)}	±(0,3 % of reading +2 °C)		
Repeatability ^{1), 3)}	±(0,1 % of reading +1 °C)		
Temperature resolution (NETD)	0,1 K		
Exposure time (90% signal) ⁴⁾	1 ms		
Emissivity/ Gain	0,100...1,100 (adjustable via programming keys or software)		
Transmissivity	0,100...1,100 (adjustable via programming keys or software)		
Signal processing	Average, peak hold, valley hold (adjustable via programming keys or software)		

¹⁾ at ambient temperature 23±5 °C

²⁾ Accuracy for thermocouple output: ±2,5 °C or ±1 %

³⁾ $\varepsilon = 1$ / Response time 1 s

⁴⁾ with dynamic adaptation at low signal levels

2.5 Measurement Specifications [3M models]

	3ML	3MH	3MH1	3MH2	3MH3
Temperature range (scalable)	50...400 °C ¹⁾	100...600 °C ¹⁾	150...1000 °C	200...1500 °C	250...1800 °C
Spectral range	2,3 µm				
Optical resolution	60:1	100:1	300:1		
System accuracy ^{2), 3), 4)}	±(0,3 % of reading +2 °C)				
Repeatability ^{2), 4)}	±(0,1 % of reading +1 °C)				
Temperature resolution (NETD) ⁴⁾	0,1 K				
Exposure time (90 % signal) ⁵⁾	1 ms				
Emissivity/ Gain	0,100...1,100 (adjustable via programming keys or software)				
Transmissivity	0,100...1,100 (adjustable via programming keys or software)				
Signal processing	Average, peak hold, valley hold (adjustable via programming keys or software)				

¹⁾ T_{Object} > T_{Head}+25 °C

²⁾ at ambient temperature 23±5 °C

³⁾ Accuracy for thermocouple output: ±2,5 °C or ±1 %

⁴⁾ ε = 1/ Response time 1 s

⁵⁾ with dynamic adaptation at low signal levels

2.6 Optical Charts

The vario optics of the CTvideo allows a smooth focusing of the optics to the desired distance. The sensors are available in two optic versions:

Optics	Focus adjustable in the range
SFV	200 mm till infinity
CFV	90 mm till 250 mm



The size of the measuring object and the optical resolution of the infrared thermometer determine the maximum distance between sensing head and measuring object.

In order to prevent measuring errors the object should fill out the field of view of the optics completely.

Consequently, the spot should at all times have at least **the same size** like the object or should be **smaller than** that.

The following tables show the diameter of the measuring spot for some selected distances. The spot size refers to 90 % of the radiation energy.

The distance is always measured from the front edge of the sensing head.

As an alternative to the optical diagrams, the spot size calculator can also be used on the optris website <http://www.optris.com/spot-size-calculator>.

3ML: SF optics (D:S=60:1)									
spot size	mm	3,3	5,0	7,5	11,7	18,3	26,7	41,7	83,3
measurement distance	mm	200	300	450	700	1100	1600	2500	5000

3ML: CF optics (D:S=60:1)								
spot size	mm	1,5	2,0	2,5	3,0	3,5	4,2	
measurement distance	mm	90	120	150	180	210	250	

3MH: SF optics (D:S=100:1)									
spot size	mm	2,0	3,0	4,5	7,0	11,0	16,0	25,0	50,0
measurement distance	mm	200	300	450	700	1100	1600	2500	5000

3MH: CF optics (D:S=100:1)								
spot size	mm	0,9	1,2	1,5	1,8	2,1	2,5	
measurement distance	mm	90	120	150	180	210	250	

1ML/2ML: SF optics (D:S=150:1)									
spot size	mm	1,3	2,0	3,0	4,7	7,3	10,7	16,7	33,3
measurement distance	mm	200	300	450	700	1100	1600	2500	5000

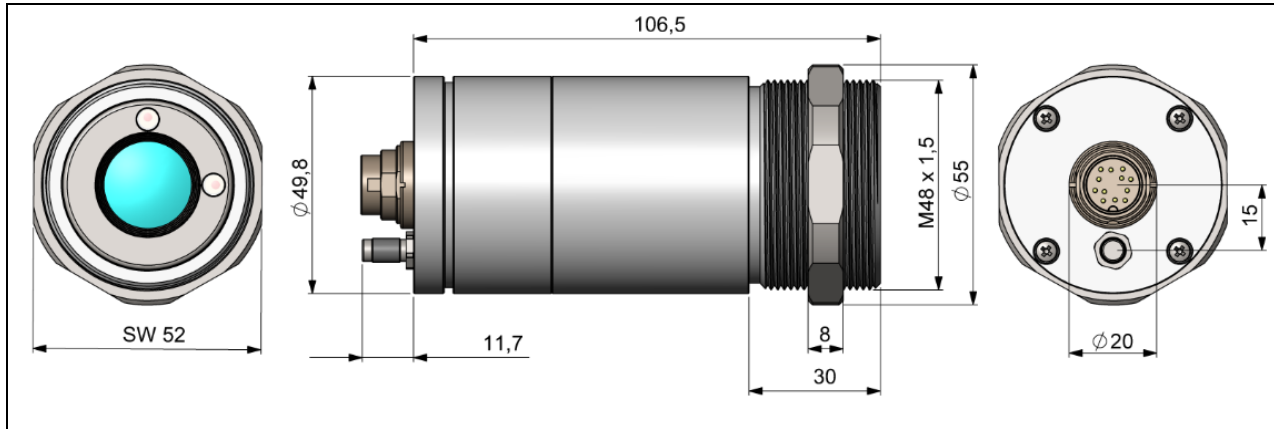
1ML/2ML: CF optics (D:S=150:1)								
spot size	mm	0,6	0,8	1,0	1,2	1,4	1,7	
measurement distance	mm	90	120	150	180	210	250	

1MH-H1/2MH-H1/3MH1-H3: SF optics (D:S=300:1)									
spot size	mm	0,7	1,0	1,5	2,3	3,7	5,3	8,3	16,7
measurement distance	mm	200	300	450	700	1100	1600	2500	5000

1MH-H1/2MH-H1/3MH1-H3: CF optics (D:S=300:1)							
spot size	mm	0,3	0,4	0,5	0,6	0,7	0,8
measurement distance	mm	90	120	150	180	210	250

3 Mechanical Installation

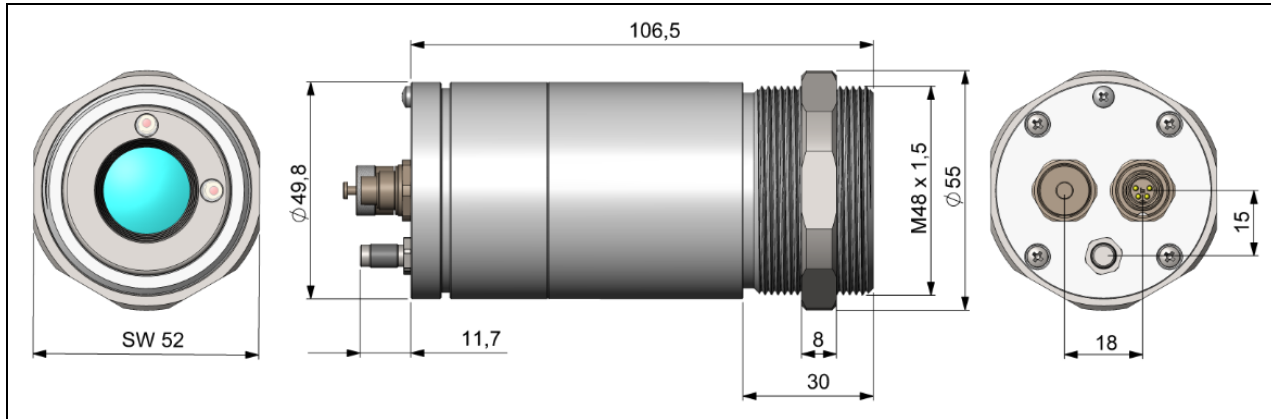
The CTvideo is equipped with a metric M48x1,5 thread and can be installed either directly via the sensor thread or with help of the supplied mounting nut (standard) and fixed mounting bracket (standard) to a mounting device available.



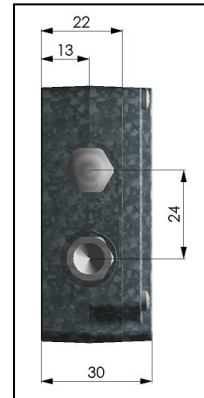
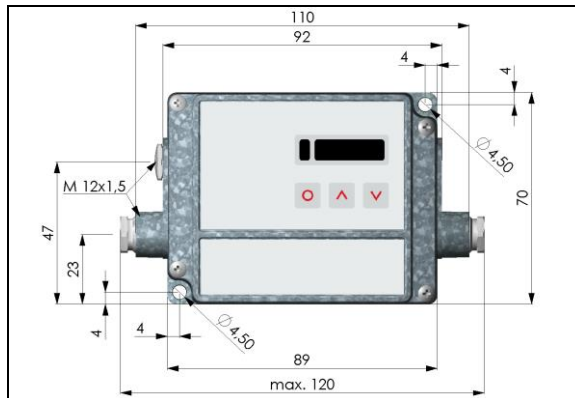
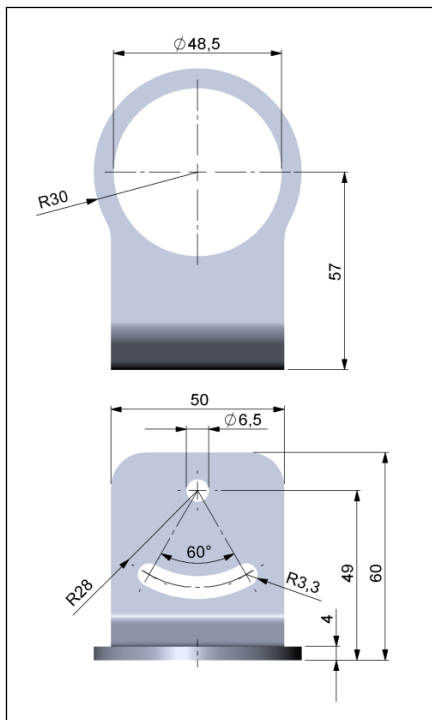
CTvideo sensing head (Basic version)



Make sure to keep the optical path clear of any obstacles.



CTvideo sensing head (High temperature version)



Electronic box



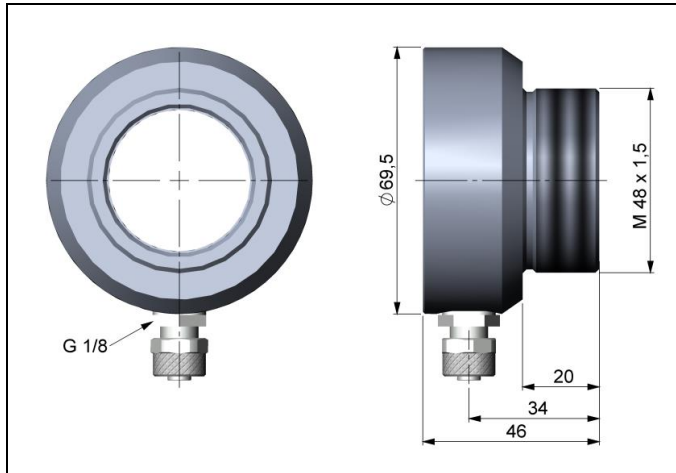
For an exact alignment of the head to the object please activate the integrated video and/ or crosshair laser sighting.
[▶7 Operating, 8 Sighting]

Mounting bracket, adjustable in one axis [ACCTLFB] – standard scope of supply

4 Accessories

4.1 Air Purge Collar

The lens must be kept clean at all times from dust, smoke, fumes and other contaminants in order to avoid reading errors. These effects can be reduced by using an air purge collar. Make sure to use oil-free, technically clean air, only.

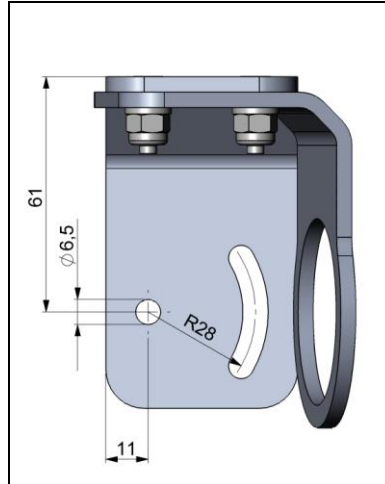
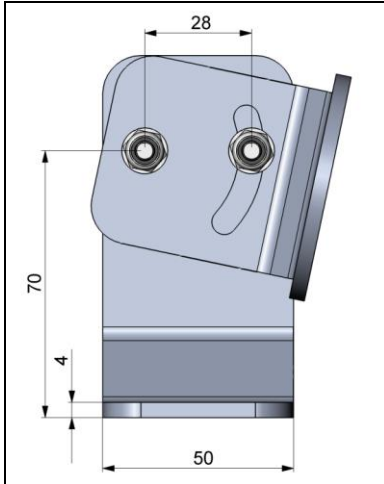


The needed amount of air (approx. 2...10 l/ min.) depends on the application and the installation conditions on-site.



Air purge collar [ACCTLAP]
Hose connection: 6x8 mm
Thread (fitting): G 1/8 inch

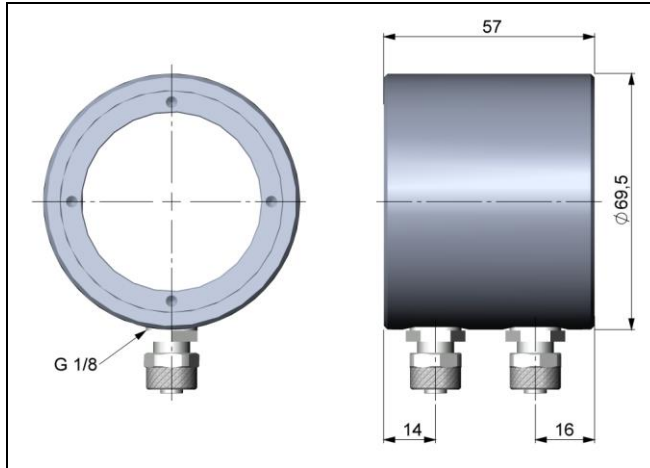
4.2 Mounting Bracket



Mounting bracket, adjustable in two axes [ACCTLAB]

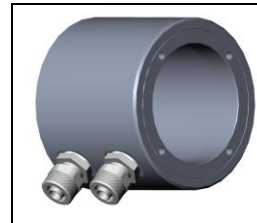
This adjustable mounting bracket allows an adjustment of the sensor in two axis.

4.3 Water Cooled Housing



To avoid condensation on the optics an air purge collar is recommended.

Water flow rate: approx. 2 l/ min
(Cooling water temperature should not exceed 30 °C)

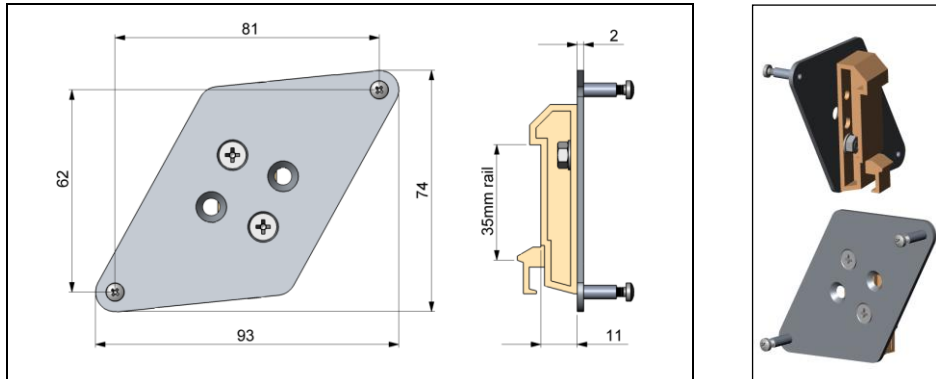


Water cooled housing [ACCTLW]
Hose connection: 6x8 mm
Thread (fitting): G 1/8 inch

The sensing head can be used at ambient temperatures up to 70 °C without cooling. For applications, where the ambient temperature can reach higher values, the usage of the optional water cooled housing is recommended (operating temperature up to 175 °C). The sensor should be equipped with the optional high temperature cables (operating temperature up to 180 °C).

4.4 Rail Mount Adapter for Electronic box

With the rail mount adapter the CTvideo electronics can be mounted easily on a DIN rail (TS35) according EN50022.



Rail mount adapter [ACCTRAIL]



► All accessories can be ordered according to the referred part numbers in brackets [].

5 Electrical Installation

5.1 Cable Connections

The CTvideo sensing heads are equipped with connectors in the backplane. Therefore an opening of the sensing head for assembling or disassembling is not necessary. An USB cable (5 m) is already connected on the electronics and can be used for linking to a computer.

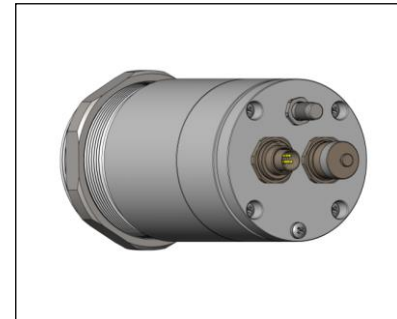
Basic version

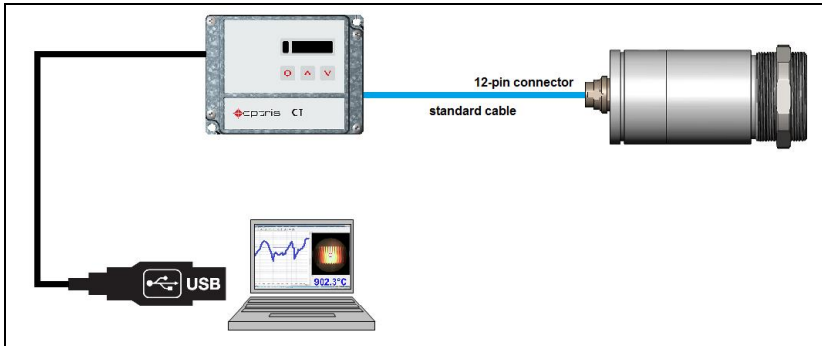
The standard version of the CTvideo has a 12-pin connector which is integrated in the sensors backplane. The connection to the electronics is done by the blue sensor cable. Cable lengths of 3 m, 5 m and 10 m are available.



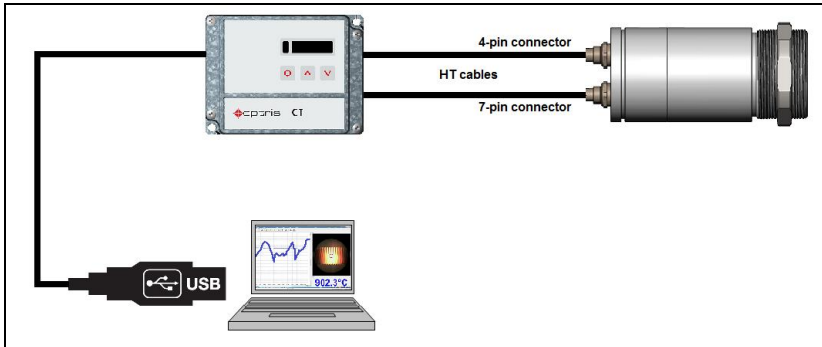
High temperature version

The high temperature version of the CTvideo has two connectors (7-pin and 5-pin) which are integrated in the sensor backplane. The connection sensing head – electronics will be done in this case via: a 7-core high temperature cable (sensor signals, laser) and a 4-core high temperature cable (video signal). Cable lengths of 3 m, 5 m and 10 m are available.





CTvideo Basic version



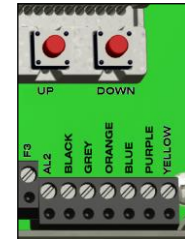
CTvideo High temperature version

Designation

+8..36 VDC	Power supply
GND	Ground (0 V) of power supply
GND	Ground (0 V) of internal in- and outputs
AL2	Alarm 2 (Open collector output)
OUT-TC	Analog output thermocouple (J or K)
OUT-mV/mA	Analog output object temperature (mV or mA)
F1-F3	Functional inputs
GND	Ground (0 V)
3V SW	BLACK/ Power supply Laser (+)
GND	GREY/ Ground Laser (-)
ORANGE	Temperature probe head (NTC)
BLUE	Head ground
PURPLE	Head power
YELLOW	Detector signal



Opened electronic box
with terminal connections



Power supply

Please use a separate, stabilized power supply unit with an output voltage of **8–36 VDC** which can supply **160 mA**. The ripple should be max. **200 mV**.

Please use shielded cables only for all power and data lines.

The sensor shield has to be grounded.



Please do never connect a supply voltage to the analog outputs as this will destroy the output!

The CTvideo is not a 2-wire sensor!

Cable Assembling

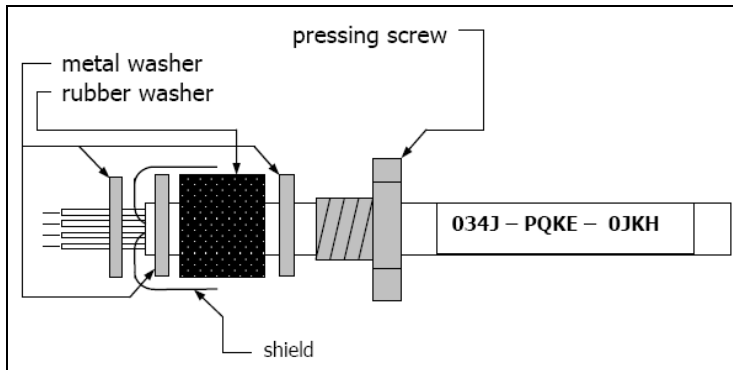
The cable gland M12x1,5 allows the use of cables with a diameter of 3 to 5 mm.

Remove the isolation from the cable (40 mm power supply, 50 mm signal outputs, 60 mm functional inputs).

Cut the shield down to approximately 5 mm and spread the strands out. Extract about 4 mm of the wire isolation and tin the wire ends.

Place the pressing screw, the rubber washer and the metal washers of the cable gland one after the other onto the prepared cable end. Spread the strands and fix the shield between two of the metal washers. Insert the cable into the cable gland until the limit stop. Screw the cap tight.

Every single wire may be connected to the according screw clamps according to their colors.

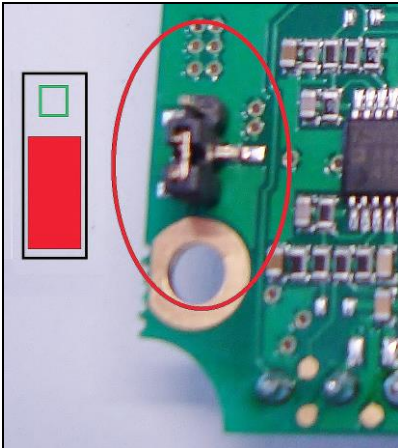


Use shielded cables only. The sensor shield has to be grounded.

5.2 Ground Connection

At the bottom side of the mainboard PCB you will find a connector (jumper) which has been placed from factory side as shown in the picture [**bottom** and **middle** pin connected]. In this position the ground connections (GND power supply/ outputs) are connected with the ground of the electronics housing. To avoid ground loops and related signal interferences in industrial environments it might be necessary to interrupt this connection. To do this please put the jumper in the opposite position [**middle** and **top** pin connected].

If the thermocouple output is used the connection GND – housing should be interrupted generally.



CTvideo mainboard

5.3 Sensing head Calibration Code

Every head has a specific calibration code, which is printed on the head. For a correct temperature measurement and functionality of the sensor this calibration code must be stored into the electronic box. The calibration code consists of five blocks with 4 characters each.

Example: **EKJ0 – 00UD – 0A1B – A17U – 93OZ**
 block1 block2 block3 block4 block5

For entering the code please press the **Up** and **Down** key (keep pressed) and then the **Mode** key. The display shows **HCODE** and then the 4 signs of the first block. With **Up** and **Down** each sign can be changed, **Mode** switches to the next sign or next block.



After you have modified the head code a reset is necessary to activate the change.
[▶ 7 Operating]



You will find the calibration code on a label fixed on the head. Please do not remove this label or make sure the code is noted anywhere.

6 Outputs and Inputs

6.1 Analog Output

This output is used for the object temperature. The selection of the output signal can be done via the programming keys [**►7 Operating**]. The CompactConnect software allows the programming of output channel 1 as an alarm output.

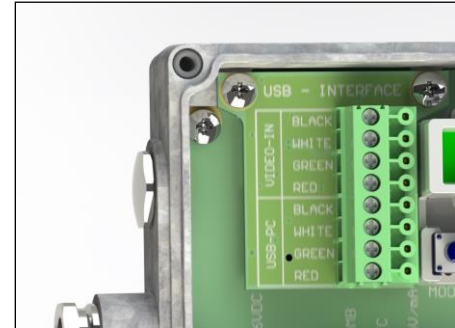
Output signal	Range	Connection pin on CTvideo board
Voltage	0 ... 5 V	OUT-mV/mA
Voltage	0 ... 10 V	OUT-mV/mA
Current	0 ... 20 mA	OUT-mV/mA
Current	4 ... 20 mA	OUT-mV/mA
Thermocouple	TC J	OUT-TC
Thermocouple	TC K	OUT-TC



According to the chosen output signal there are different connection pins on the mainboard (**OUT-mV/mA** or **OUT-TC**).

6.2 Digital Interface

The CTvideo sensors are equipped with an USB interface. The interface board is located beside the LCD display. To uninstall the board please disconnect both of the M3x5 screws. Please pay attention to the correct positioning of the pin strip if you install the board.



6.3 Functional Inputs

The three functional inputs F1 – F3 can be programmed with the CompactConnect software, only.

F1 (digital): trigger (a 0 V level on F1 resets the hold functions)

F2 (analog): external emissivity adjustment [0–10 V: 0 V ► $\epsilon=0,1$; 9 V ► $\epsilon=1$; 10 V ► $\epsilon=1,1$]

F3 (analog): external compensation of ambient temperature/ the range is scalable via software
[0–10 V ► -40–900 °C / preset range: -20–200 °C]

F1-F3 (digital): emissivity (digital choice via table)

A non connected input represents:

F1=High | F2, F3=Low.

[High level: $\geq +3$ V...+36 V | Low level: $\leq +0,4$ V...-36 V]

6.4 Alarms

The CTvideo has the following Alarm features:

All alarms (alarm 1, alarm 2, output channel 1 and 2 if used as alarm output) have a fixed **hysteresis of 2 K**.

Output channel 1

To activate the alarm function the output channel has to be switched into digital mode. For this purpose the software CompactConnect is required.

Visual Alarms

These alarms will cause a change of the color of the LCD display and will also change the status of the optional relays interface. In addition the Alarm 2 can be used as open collector output at pin **AL2** on the mainboard [**24 V / 50 mA**].

From factory side the alarms are defined as follows:

Alarm 1	Norm. closed/ Low-Alarm
Alarm 2	Norm. open/ High-Alarm

Both of these alarms will have effect on the LCD color:

BLUE:	alarm 1 active
RED:	alarm 2 active
GREEN:	no alarm active

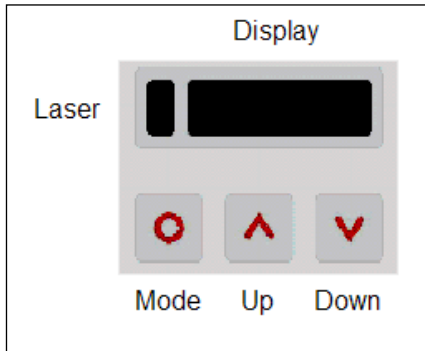
Extended setup like definition as low or high alarm [**via change of normally open/ closed**], selection of the signal source [**T_{Obj}, T_{Head}, T_{Box}**] can be done with the software CompactConnect.

7 Operating

After power up the unit the sensor starts an initializing routine for some seconds. During this time the display will show **INIT**. After this procedure the object temperature is shown in the display. The display backlight color changes according to the alarm settings [► **6.4 Alarms**].

7.1 Sensor Setup

The programming keys **Mode**, **Up** and **Down** enable the user to set the sensor on-site. The current measuring value or the chosen feature is displayed. With **Mode** the operator obtains the chosen feature, with **Up** and **Down** the functional parameters can be selected – **a change of parameters will have immediate effect**. If no key is pressed for more than 10 seconds the display automatically shows the calculated object temperature (according to the signal processing).



Pressing the Mode button again recalls the last called function on the display. The signal processing features **Peak hold** and **Valley hold** cannot be selected simultaneously.

Factory Default Setting

To set the CTvideo back to the factory default settings, please press at first the **Down**-key and then the **Mode**-key and keep both pressed for approx. 3 seconds. The display will show **RESET** for confirmation.

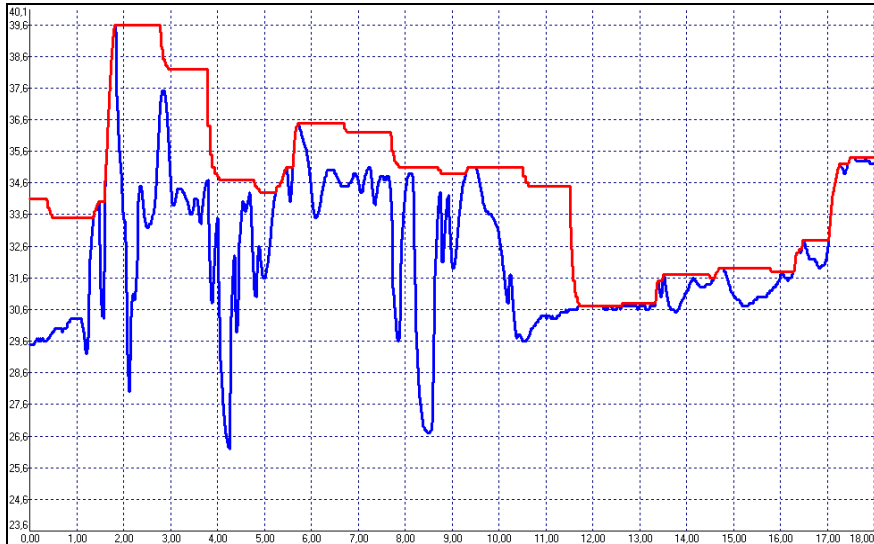
Display	Mode [Sample]	Adjustment Range
S ON	Laser Sighting [On]	ON/ OFF
142.3C	Object temperature (after signal processing) [142,3 °C]	fixed
127CH	Head temperature [127 °C]	fixed
25CB	Box temperature [25 °C]	fixed
142CA	Current object temperature [142 °C]	fixed
<input type="checkbox"/> MV5	Signal output channel 1 [0-5 V]	<input type="checkbox"/> 0-20 = 0–20 mA/ <input type="checkbox"/> 4-20 = 4–20 mA/ <input type="checkbox"/> MV5 = 0–5 V/ <input type="checkbox"/> MV10 = 0-10 V/ <input type="checkbox"/> TCJ = thermocouple type J/ <input type="checkbox"/> TCK = thermocouple type K
E0.970	Emissivity [0,970]	0,100 ... 1,100
T1.000	Transmissivity [1,000]	0,100 ... 1,100
A 0.2	Signal output Average [0,2 s]	A---- = inactive/ 0,1 ... 999,9 s
P----	Signal output Peak hold [inactive]	P---- = inactive/ 0,1 ... 999,9 s / P oo oo oo oo = infinite
V----	Signal output Valley hold [inactive]	V---- = inactive/ 0,1 ... 999,9 s / V oo oo oo oo = infinite
u 0.0	Lower limit temperature range [0 °C]	depending on model / inactive at TCJ- and TCK-output
n 500.0	Upper limit temperature range [500 °C]	depending on model / inactive at TCJ- and TCK-output
[0.00	Lower limit signal output [0 V]	according to the range of the selected output signal
] 5.00	Upper limit signal output [5 V]	according to the range of the selected output signal
U °C	Temperature unit [°C]	°C/ °F
 30.0	Lower alarm limit [30 °C]	depending on model
 100.0	Upper alarm limit [100 °C]	depending on model
XHEAD	Ambient temperature compensation [head temperature]	XHEAD = head temperature/ -40,0 ... 900,0 °C (for LT) as fixed value for compensation/ returning to XHEAD (head temperature) by pressing Up and Down together
M 01	Multidrop adress [1] (only with RS485 interface)	01 ... 32
B 9.6	Baud rate in kBaud [9,6]	9,6/ 19,2/ 38,4/ 57,6/ 115,2 kBaud

- S ON** Activating (**ON**) and Deactivating (**OFF**) of the **Sighting Laser**. By pressing **Up** or **Down** the laser can be switched on and off.
- MV5** Selection of the **Output signal**. By pressing **Up** or **Down** the different output signals can be selected (see table).
- E0.970** Setup of **Emissivity**. Pressing **Up** increases the value, **Down** decreases the value (also valid for all further functions). The emissivity is a material constant factor to describe the ability of the body to emit infrared energy [**► 11 Emissivity**].
- T1.000** Setup of **Transmissivity**. This function is used if an optical component (protective window, additional optics e.g.) is mounted between sensor and object. The standard setting is 1.000 = 100 % (if no protective window etc. is used).
- A 0.2** Setup of **Average time**. In this mode an arithmetic algorithm will be performed to smoothen the signal. The set time is the time constant. This function can be combined with all other post processing functions. The shortest value is 0,001 s and can be increased/ decreased only by values of the power series of 2 (0,002, 0,004, 0,008, 0,016, 0,032, ...).
If the value is set to **0.0** the display will show --- (function deactivated).
- P----** Setup of **Peak hold**. In this mode the sensor is waiting for descending signals. If the signal descends the algorithm maintains the previous signal peak for the specified time. After the hold time the signal will drop down to the second highest value or will descend by 1/8 of the difference between the previous peak and the minimum value during the hold time. This value will be held again for the specified time. After this the signal will drop down with slow time constant and will follow the current object temperature.
If the value is set to **0.0** the display will show --- (function deactivated).

V----

Setup of **Valley hold**. In this mode the sensor waits for ascending signals. The definition of the algorithm is according to the peak hold algorithm (inverted).
If the value is set to **0.0** the display will show --- (function deactivated).

Signal graph with P----



- TProcess with Peak Hold (Hold time = 1s)
- TActual without post processing

- u 0.0** Setup of the **Lower limit of temperature range**. The minimum difference between lower and upper limit is **20 K**. If you set the lower limit to a value \geq upper limit the upper limit will be adjusted to **[lower limit + 20 K]** automatically.
- n 500.0** Setup of the **Upper limit of the temperature range**. The minimum difference between upper and lower limit is **20 K**. The upper limit can only be set to a value = lower limit + 20 K.
- l 0.00** Setup of the **Lower limit of the signal output**. This setting allows an assignment of a certain signal output level to the lower limit of the temperature range. The adjustment range corresponds to the selected output mode (e.g. 0-5 V).
- l 5.00** Setup of the **Upper limit of the signal output**. This setting allows an assignment of a certain signal output level to the upper limit of the temperature range. The adjustment range corresponds to the selected output mode (e.g. 0-5 V).
- U °C** Setup of the **Temperature unit** [°C or °F].
- | 30.0** Setup of the **Lower alarm limit**. This value corresponds to Alarm 1 [**► 6.4 Alarms**] and is also used as threshold value for relay 1 (if the optional relay board is used).
- || 100.0** Setup of the **Upper alarm limit**. This value corresponds to Alarm 2 [**► 6.4 Alarms**] and is also used as threshold value for relay 2 (if the optional relay board is used).
- XHEAD** Setup of the **Ambient temperature compensation**. In dependence on the emissivity value of the object a certain amount of ambient radiation will be reflected from the object surface. To compensate this impact, this function allows the setup of a fixed value which represents the ambient radiation.

If **XHEAD** is shown the ambient temperature value will be taken from the head-internal probe.

To return to **XHEAD** please press **Up** and **Down** together.



Especially if there is a big difference between the ambient temperature at the object and the head temperature the use of **Ambient temperature compensation** is recommended.

M 01

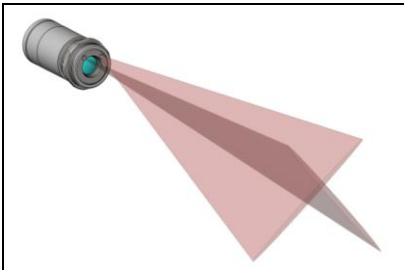
Setup of the **Multidrop address**. In a RS485 network each sensor will need a specific address. This menu item will only be shown if a RS485 interface board is plugged in.

B 9.6

Setup of the **Baud rate** for digital data transfer.

8 Sighting

The CTvideo has an integrated video camera which is using the same optical channel than the IR detector. In addition the sensor has a cross laser aiming which marks the center of the measurement spot at any distance. The combination of video and laser sighting enables a perfect alignment of the sensor to the object.



Do not point the laser directly at the eyes of persons or animals! Do not stare into the laser beam. Avoid indirect exposure via reflective surfaces!

The laser can be activated/ deactivated via the programming keys on the unit or via the software. If the laser is activated a yellow LED will shine (beside temperature display).

At ambient temperatures >50 °C the laser will be switched off automatically.

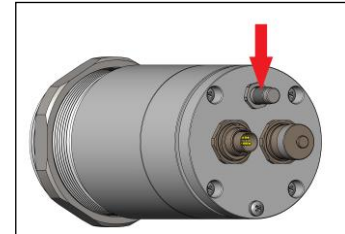


The laser should only be used for sighting and positioning of the sensor. A permanent use of the laser can reduce the lifetime of the laser diodes and also the measurement accuracy can be affected.

8.1 Focusing and Video Sighting

On the back plane of the sensor you will find a rotary button for focusing of the optics.

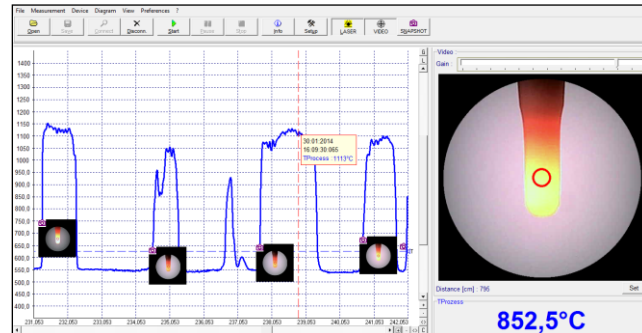
To set the focus to the desired measurement distance you have to connect the sensor with a PC using the USB cable. Please start the CompactConnect software. You will see the video beside the temperature-time diagram. The position of the measurement spot is indicated by a circle inside the video picture. The size of this circle is equivalent to the IR spot size.



By turning the rotary button **clockwise** you will change the focus in direction **far**. By turning **counterclockwise** you will change the focus in direction **close**.

After a successful focusing please enter the measurement distance (distance sensor front – object) in the according field in the software (underneath the video picture).

You will find a detailed description of the video settings in the software description which you can call via the menu **[? / Help...]**.



8.2 Error messages

The display of the sensor can show the following error messages:

1. Digit:

0x	No error
1x	Head temperature probe short circuit to GND
2x	Box temperature too low
4x	Box temperature too high
6x	Box temperature probe disconnected
8x	Box temperature probe short circuit to GND

2. Digit:

x0	No error
x2	Object temperature too high
x4	Head temperature too low
x8	Head temperature too high
xC	Head temperature probe disconnected

9 Software CompactConnect

9.1 Installation

Insert the installation CD into the according drive on your computer. If the autorun option is activated the installation wizard will start automatically.

Otherwise please start **CDsetup.exe** from the CD-ROM. Follow the instructions of the wizard until the installation is finished.

The installation wizard will place a launch icon on the desktop and in the start menu:

[Start]\Programs\CompactConnect.

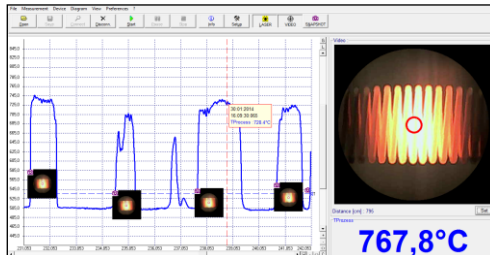
If you want to uninstall the software from your system please use the **uninstall icon** in the start menu.

Min. system requirements:

- Windows XP, Vista, 7, 8, 10
- USB interface
- Hard disc with at least 30 MByte free space
- At least 128 MByte RAM
- CD-ROM drive



You will find a detailed software manual on the CD.



Main Features:

- Alignment of the sensor
- Graphic display for temperature trends and automatic data logging and video snapshot generation for analysis and documentation
- Complete sensor setup and remote controlling
- Adjustment of signal processing functions
- Programming of outputs and functional inputs

9.2 Communication Settings

Serial Interface

Baud rate: 9,6...115,2 kBaud (adjustable on the unit or via software)
Data bits: 8
Parity: none
Stop bits: 1
Flow control: off

Protocol

All sensors of the CTvideo series are using a binary protocol. Alternatively they can be switched to an ASCII protocol. To get a fast communication the protocol has no additional overhead with CR, LR or ACK bytes.

ASCII protocol

To switch to the ASCII protocol please use the following command:

Decimal: 131
HEX: 0x83
Data, Answer: byte 1
Result: 0 – Binary protocol
1 – ASCII protocol

Saving of parameter settings

After power on of the CTvideo sensor the flash mode is active. It means, changed parameter settings will be saved in the internal Flash-EEPROM and will be kept also after the sensor is switched off.

In case settings should be changed quite often or continuously the flash mode can be switched off by using the following command:

Decimal: **112**
HEX: **0x70**
Data, Answer: **byte 1**
Result: **0 – Data will not be written into the flash memory**
 1 – Data will be written into the flash memory

If the flash mode is deactivated, all settings will only be kept as long as the unit is powered. If the unit is switched off and powered on again all previous settings are lost.

The command 0x71 will poll the current status.

You will find a detailed protocol and command description on the software CD CompactConnect in the directory: **\Commands**.

10 Basics of Infrared Thermometry

Depending on the temperature each object emits a certain amount of infrared radiation. A change in the temperature of the object is accompanied by a change in the intensity of the radiation. For the measurement of “thermal radiation” infrared thermometry uses a wave-length ranging between 1 μm and 20 μm .

The intensity of the emitted radiation depends on the material. This material contingent constant is described with the help of the emissivity which is a known value for most materials (► **11 Emissivity**).

Infrared thermometers are optoelectronic sensors. They calculate the surface temperature on the basis of the emitted infrared radiation from an object. The most important feature of infrared thermometers is that they enable the user to measure objects contactless. Consequently, these products help to measure the temperature of inaccessible or moving objects without difficulties. Infrared thermometers basically consist of the following components:

- lens
- spectral filter
- detector
- electronics (amplifier/ linearization/ signal processing)

The specifications of the lens decisively determine the optical path of the infrared thermometer, which is characterized by the ratio Distance to Spot size.

The spectral filter selects the wavelength range, which is relevant for the temperature measurement. The detector in cooperation with the processing electronics transforms the emitted infrared radiation into electrical signals.

11 Emissivity

11.1 Definition

The intensity of infrared radiation, which is emitted by each body, depends on the temperature as well as on the radiation features of the surface material of the measuring object. The emissivity (ϵ – Epsilon) is used as a material constant factor to describe the ability of the body to emit infrared energy. It can range between 0 and 100 %. A “blackbody” is the ideal radiation source with an emissivity of 1,0 whereas a mirror shows an emissivity of 0,1.

If the emissivity chosen is too high, the infrared thermometer may display a temperature value which is much lower than the real temperature – assuming the measuring object is warmer than its surroundings. A low emissivity (reflective surfaces) carries the risk of inaccurate measuring results by interfering infrared radiation emitted by background objects (flames, heating systems, chamottes). To minimize measuring errors in such cases, the handling should be performed very carefully and the unit should be protected against reflecting radiation sources.

11.2 Determination of unknown Emissivities

- ▶ First, determine the actual temperature of the measuring object with a thermocouple or contact sensor. Second, measure the temperature with the infrared thermometer and modify the emissivity until the displayed result corresponds to the actual temperature.
- ▶ If you monitor temperatures of up to 380 °C you may place a special plastic sticker (emissivity dots – part number: ACLSED) onto the measuring object, which covers it completely. Now set the emissivity to 0,95

and take the temperature of the sticker. Afterwards, determine the temperature of the adjacent area on the measuring object and adjust the emissivity according to the value of the temperature of the sticker.

- ▶ Cove a part of the surface of the measuring object with a black, flat paint with an emissivity of 0,98. Adjust the emissivity of your infrared thermometer to 0,98 and take the temperature of the colored surface. Afterwards, determine the temperature of a directly adjacent area and modify the emissivity until the measured value corresponds to the temperature of the colored surface.

CAUTION: On all three methods the object temperature must be different from ambient temperature.

11.3 Characteristic Emissivities

In case none of the methods mentioned above help to determine the emissivity you may use the emissivity tables ▶ **Appendix A – Emissivity Table Metals** and **Appendix B – Emissivity Table Non Metals**. These are average values only. The actual emissivity of a material depends on the following factors:

- temperature
- measuring angle
- geometry of the surface
- thickness of the material
- constitution of the surface (polished, oxidized, rough, sandblast)
- spectral range of the measurement
- transmissivity (e.g. with thin films)

Appendix A – Emissivity Table Metals

Material		typical Emissivity			
Spectral response		1,0 μm	1,6 μm	5,1 μm	8-14 μm
Aluminium	non oxidized	0,1-0,2	0,02-0,2	0,02-0,2	0,02-0,1
	polished	0,1-0,2	0,02-0,1	0,02-0,1	0,02-0,1
	roughened	0,2-0,8	0,2-0,6	0,1-0,4	0,1-0,3
	oxidized	0,4	0,4	0,2-0,4	0,2-0,4
Brass	polished	0,35	0,01-0,05	0,01-0,05	0,01-0,05
	roughened	0,65	0,4	0,3	0,3
	oxidized	0,6	0,6	0,5	0,5
Copper	polished	0,05	0,03	0,03	0,03
	roughened	0,05-0,2	0,05-0,2	0,05-0,15	0,05-0,1
	oxidized	0,2-0,8	0,2-0,9	0,5-0,8	0,4-0,8
Chrome		0,4	0,4	0,03-0,3	0,02-0,2
Gold		0,3	0,01-0,1	0,01-0,1	0,01-0,1
Haynes	alloy	0,5-0,9	0,6-0,9	0,3-0,8	0,3-0,8
Inconel	electro polished	0,2-0,5	0,25	0,15	0,15
	sandblast	0,3-0,4	0,3-0,6	0,3-0,6	0,3-0,6
	oxidized	0,4-0,9	0,6-0,9	0,6-0,9	0,7-0,95
Iron	non oxidized	0,35	0,1-0,3	0,05-0,25	0,05-0,2
	rusted		0,6-0,9	0,5-0,8	0,5-0,7
	oxidized	0,7-0,9	0,5-0,9	0,6-0,9	0,5-0,9
	forged, blunt	0,9	0,9	0,9	0,9
	molten	0,35	0,4-0,6		
Iron, casted	non oxidized	0,35	0,3	0,25	0,2
	oxidized	0,9	0,7-0,9	0,65-0,95	0,6-0,95

Material		typical Emissivity			
		1,0 μm	1,6 μm	5,1 μm	8-14 μm
Lead	polished	0,35	0,05-0,2	0,05-0,2	0,05-0,1
	roughened	0,65	0,6	0,4	0,4
	oxidized		0,3-0,7	0,2-0,7	0,2-0,6
Magnesium		0,3-0,8	0,05-0,3	0,03-0,15	0,02-0,1
Mercury			0,05-0,15	0,05-0,15	0,05-0,15
Molybdenum	non oxidized	0,25-0,35	0,1-0,3	0,1-0,15	0,1
	oxidized	0,5-0,9	0,4-0,9	0,3-0,7	0,2-0,6
Monel (Ni-Cu)		0,3	0,2-0,6	0,1-0,5	0,1-0,14
Nickel	electrolytic	0,2-0,4	0,1-0,3	0,1-0,15	0,05-0,15
	oxidized	0,8-0,9	0,4-0,7	0,3-0,6	0,2-0,5
Platinum	black		0,95	0,9	0,9
Silver		0,04	0,02	0,02	0,02
Steel	polished plate	0,35	0,25	0,1	0,1
	rustless	0,35	0,2-0,9	0,15-0,8	0,1-0,8
	heavy plate			0,5-0,7	0,4-0,6
	cold-rolled	0,8-0,9	0,8-0,9	0,8-0,9	0,7-0,9
	oxidized	0,8-0,9	0,8-0,9	0,7-0,9	0,7-0,9
Tin	non oxidized	0,25	0,1-0,3	0,05	0,05
Titanium	polished	0,5-0,75	0,3-0,5	0,1-0,3	0,05-0,2
	oxidized		0,6-0,8	0,5-0,7	0,5-0,6
Wolfram	polished	0,35-0,4	0,1-0,3	0,05-0,25	0,03-0,1
Zinc	polished	0,5	0,05	0,03	0,02
	oxidized	0,6	0,15	0,1	0,1

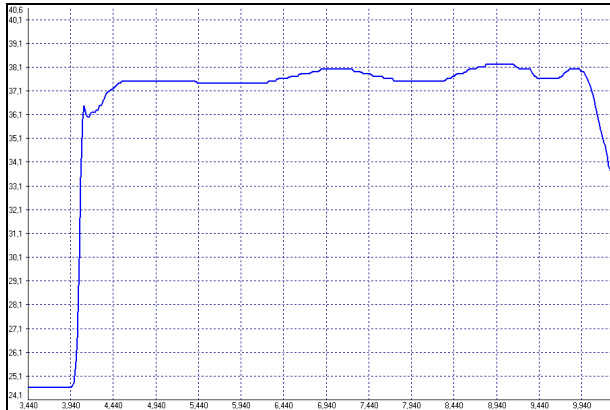
Appendix B – Emissivity Table Non Metals

Material	typical Emissivity				
	Spectral response	1,0 μm	2,2 μm	5,1 μm	8-14 μm
Asbestos		0,9	0,8	0,9	0,95
Asphalt				0,95	0,95
Basalt				0,7	0,7
Carbon	non oxidized		0,8-0,9	0,8-0,9	0,8-0,9
	graphite		0,8-0,9	0,7-0,9	0,7-0,8
Carborundum			0,95	0,9	0,9
Ceramic		0,4	0,8-0,95	0,8-0,95	0,95
Concrete		0,65	0,9	0,9	0,95
Glass	plate		0,2	0,98	0,85
	melt		0,4-0,9	0,9	
Grit				0,95	0,95
Gypsum				0,4-0,97	0,8-0,95
Ice					0,98
Limestone				0,4-0,98	0,98
Paint	non alkaline				0,9-0,95
Paper	any color			0,95	0,95
Plastic >50 μm	non transparent			0,95	0,95
Rubber				0,9	0,95
Sand				0,9	0,9
Snow					0,9
Soil					0,9-0,98
Textiles				0,95	0,95
Water					0,93
Wood	natural			0,9-0,95	0,9-0,95

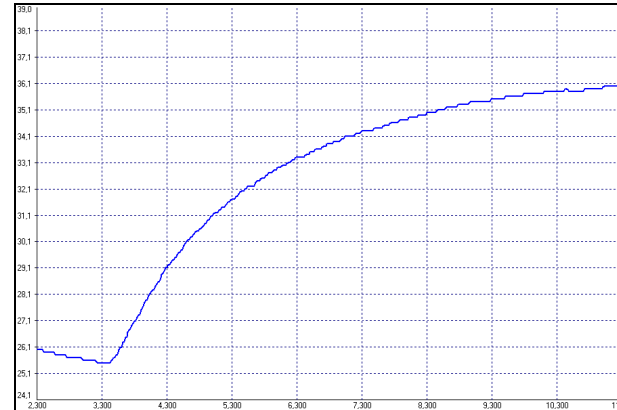
Appendix C – Smart Averaging

The average function is generally used to smoothen the output signal. With the adjustable parameter time this function can be optimal adjusted to the respective application. One disadvantage of the average function is that fast temperature peaks which are caused by dynamic events are subjected to the same averaging time. Therefore those peaks can only be seen with a delay on the signal output.

The function **Smart Averaging** eliminates this disadvantage by passing those fast events without averaging directly through to the signal output.





Signal graph with Smart Averaging function



Signal graph without Smart Averaging function

Appendix D – Declaration of Conformity

<p>EG-Konformitätserklärung EU Declaration of Conformity</p>	
Wir / We	<p>Optris GmbH Ferdinand Buisson Str. 14 D-13127 Berlin</p>
erklären in alleiniger Verantwortung, dass declare on our own responsibility that	<p>die Produktserie optris CTvideo the product group optris CTvideo</p>
den Anforderungen der EMV-Richtlinie 2014/30/EU und der Niederspannungsrichtlinie 2014/35/EU entspricht. meets the provisions of the EMC Directive 2014/30/EU and the Low Voltage Directive 2014/35/EU.	
Angewandte harmonisierte Normen: Applied harmonized standards:	
EMV Anforderungen / EMC General Requirements: EN 61326-1:2013 (Grundlegende Prüfanforderungen / Basic requirements) EN 61326-2-3:2013	
Gerätesicherheit von Messgeräten / Safety of measurement devices:	
EN 61010-1:2010 EN 60825-1:2015 (Lasersicherheit / Laser safety)	
Dieses Produkt erfüllt die Vorschriften der Richtlinie 2011/65/EU (RoHS) des Europäischen Parlaments und des Rates vom 8. Juni 2011 zur Beschränkung der Verwendung bestimmter gefährlicher Stoffe in Elektro- und Elektronikgeräten. This product is in conformity with Directive 2011/65/EU (RoHS) of the European Parliament and of the Council of 8 June 2011 on the restriction of the use of certain hazardous substances in electrical and electronic equipment.	
Berlin, 04.11.2015	<p>Dr. Ulrich Kientz Geschäftsführer / General Manager</p>
Ort, Datum / place, date	

optris CTvideo – E2017-08-A